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SLICE Free Motion Headform User's Manual



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DTS Support

SLICE data acquisition systems are designed to be reliable and simple to operate. Should you need assistance, DTS has support engineers worldwide with extensive product knowledge and test experience to help via telephone, e-mail or on-site visits.

The best way to contact a DTS support engineer is to e-mail support@dtsweb.com. Your e-mail is immediately forwarded to all DTS support engineers worldwide and is typically the fastest way to get a response, particularly if you need assistance outside of normal business hours. For assistance by telephone, please go to <http://dtsweb.com/support/techsupport.php> to find the phone number appropriate for your region of the world.

Introducing the SLICE Free Motion Headform (FMH) System

The SLICE FMH system is a miniature data acquisition system (DAS) designed for integration into a dummy head. It includes a battery sufficient to run the system for up to 20 minutes and supports autonomous operation after arming. After the test, reconnecting the system to a PC and the provided power supply allows data download, viewing and post-processing, and recharges the battery for the next use.

Overview of SLICE FMH System

A typical 3-channel system is discussed below. Your system may vary if you have additional channels or custom features.

Detailed assembly procedures can be found in *Appendix C: SLICE FMH Assembly Procedure*.



Figure 1: 3-channel SLICE NANO Stack for FMH

13000-20010: SLICE NANO Base (1 each)

13000-20022: SLICE NANO Bridge (1 each)

13000-20090: SLICE FMH Stack Battery (1 each)

SLICE NANO Stack Cover (1 each) and Mounting Screws (2 each)

Figure 1 shows a typical 3-channel, SLICE FMH Stack that includes a Base SLICE, Bridge SLICE, SLICE FMH Stack Battery, stack cover plate, and two M3 x 35 mm or 4-40 x 1-3/8" mounting screws.

Detailed specifications for the Base SLICE and Bridge SLICE can be found on page 16 (*Appendix A: SLICE Hardware Specifications*) or at www.dtsweb.com. Details on the SLICE FMH Stack Battery can be found on page 8 (*Power/Charging Requirements*). For information on operation of the SLICE system, please see the [SLICE User's Manual](#).



The 12-socket connectors are functionally identical.

Figure 2: FMH Interface

13000-30700: SLICE FMH LED Pushbutton Cable Assembly

This cable (Figure 3) is used inside the dummy head and connects to the 5-socket connector shown in Figure 2 and the FMH skull. The pushbutton enables the auto-arm sequence and the LED provides information on arming status. Additional information on the LED can be found on page 8 (*Status LED*); details on arming the system begin on page 11 (*How to Auto-Arm the SLICE FMH System*).



Figure 3: 13000-30700 Cable Assembly

13000-30680: Cable, FMH interface to SLICE system (1 each)

This cable is used inside the FMH skull (Figure 4) and connects to either 12-socket connector shown in Figure 2. It terminates at the inside of the skull cap plate and mates with 13000-30670.



Figure 4: 13000-30680 Cable Assembly

13000-30670: Cable, FMH interface to PC + power (1 each)

This cable (Figure 5) connects to the USB port on your PC and the power supply provided with your system. It mates with 13000-30680 as it exits the skull cap plate.



Figure 5: 13000-30670 Cable and Interface

13000-30541: 12 V, 2.5 A power supply (90-240 VAC input) (1 each)

A 12 V, 2.5 A power supply (Figure 6) is provided with your system. It will simultaneously charge the battery and power the SLICE FMH system until it is disconnected prior to the test. Battery capacity and charging requirements can be found on page 8 (*Power/Charging Requirements*).



Figure 6: 13000-30541 Power Supply

13000-30120: SLICE 1 Channel Sensor Connector Assembly (3 each)

Three, 7-pin, sensor connectors with back shell and ID are provided for use with your sensors. If not included separately, these are already installed on your sensors.

13000-30131: SLICE 1 Channel Connector Cable Assembly (1 each)

This 7-socket, 50 cm cable assembly is provided to facilitate sensor calibration. It is provided without terminations to allow the user the option of attaching a connector of their choice. Sensors can then be disconnected individually from the Bridge SLICE and calibrated with the use of this cable. A termination drawing can be found on page 17 (*13000-30131 Termination Specifications*).

FMH Skull Cap Plate (1 each)

This was provided with your Free Motion Headform. You may be provided a new plate that has been modified to accept cable 13000-30680 (FMH interface to SLICE system) and to compensate for the added mass of the SLICE FMH system, or your plate may

need to be modified. Please contact your SLICE FMH system integrator or FMH vendor for additional information.

Communications

A USB-to-PC communication and power cable (DTS P/N 13000-30670) is provided with your system. All communication signals and power/battery charging are supported via the LEMO interface (Figure 4). Information on installing the software, initializing the system, downloading and viewing the data begins on page 10 (*SLICEWare Software*).

Power/Charging Requirements

The SLICE FMH Stack Battery contains an integrated, 8.4 V, 80 mAh, rechargeable lithium battery sufficient to operate the system for cable-free testing. When the 12 V, 2.5 A power supply is connected to your system, it will simultaneously charge the battery and power the SLICE FMH system until it is disconnected prior to the test.

Battery life (fully charged)	Up to 20 minutes (full sensor load)
Charge time	~1 hour from complete discharge to full charge; always charges when connected to power supply

Charging the system using a maximum of 12 V and without the USB connected minimizes system self-heating. Additional details can be found in Appendix D.

Status LED

This LED is blue and provides information on arming and recording status. It is on, off or blinking.

 Blinking	After unit is turned on, LED will blink during sensor warm-up and system arming.
 ON	If armed in Circular Buffer mode, the LED will begin recording after sensor warm-up and the LED will go solid blue. The LED will also go solid blue in Recorder mode if the system received a START signal.
 OFF	If armed in Recorder Mode, the system will stop blinking and go OFF, waiting for a START signal to begin recording.

Circular Buffer Mode	Recorder Mode
 (rate increases) Arming; sensor warm-up (~30 sec)	
<p data-bbox="456 348 667 384">  (LED is ON) System is recording </p> 	<p data-bbox="1016 348 1243 384">  (LED is OFF) Waiting for START signal </p> 
<p data-bbox="394 779 1260 890">  (rate steady) If the LED continues to blink after 45 sec, the system did not initialize properly. See page 12 (<i>Troubleshooting</i>). </p>	

To arm the system, press and hold the LED pushbutton switch for ≥ 3 sec. After 7 sec, the LED will begin to blink, indicating the system is performing the auto-arm initialization sequence. After 32 sec, the LED will be either on (circular buffer mode) or off (recorder mode). *Note: The SLICE FMH system's auto-arm feature must be software-enabled prior to pushbutton initialization.* Only Circular Buffer mode is recommended for use with the FMH. Details on software installation and use begin on page 10 (*SLICEWare Software*).

Basic Care and Handling

The SLICE FMH system is a high precision measurement instrument, designed to operate reliably in dynamic testing environments. Though resistant to many environmental conditions, care should be taken not to subject the unit to harsh chemicals, submerge it in water, or use it in a manner inconsistent with its intended purpose.

The Base SLICE, Bridge SLICE and SLICE FMH Stack Battery are supplied with calibration data from the factory. DTS recommends annual recalibration to ensure that the system is performing within factory specifications. SLICE hardware is not user-serviceable and should be returned to DTS for service or repair.

Shock Rating

The SLICE FMH system is rated for 500 g, 4 ms duration, in all axes. All mounting considerations should be thoroughly addressed to ensure the system is adequately integrated to survive the expected shock loads.

Mounting Considerations

To provide the best shock protection, the system should be securely bolted inside the FMH skull using the proper hardware and recommended torque specifications. Care must be taken to restrain the cables to permit adequate strain relief and minimal movement upon impact.

Thermal Considerations

The SLICE DAS is an extremely low power system with negligible self-heating. Should any self-heating be a concern, this can be addressed by charging the system properly and minimizing the time it takes to arm the system and perform the test (see Appendix D). Should you have any questions about using SLICE in your environment, please contact DTS.

SLICEWare Software

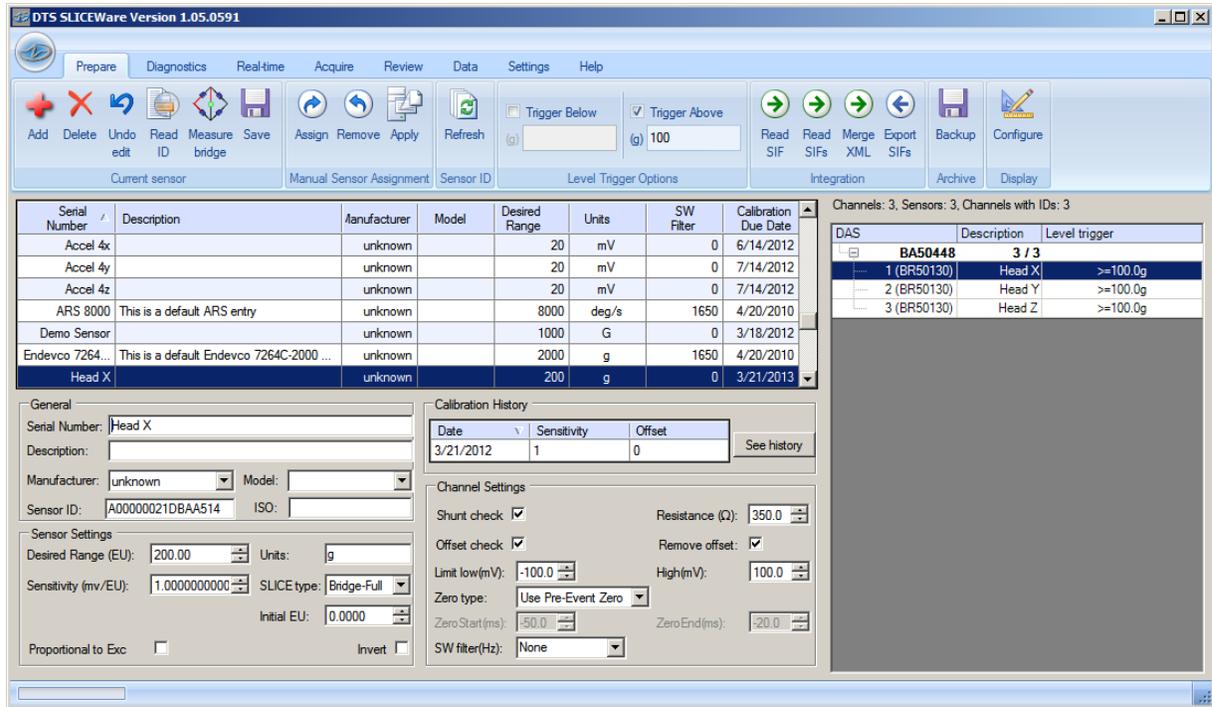
Software Installation

1. Locate the set-up.exe file on the CD or USB drive provided. Double-click the file to begin the installation and follow the prompts on your screen.
2. When installation is complete, copy the XML file found in the folder "*copy contents to SLICEWare directory after software install*" to the SLICEWare directory. (The XML file contains the sensor information.) If you were not provided an XML file, you will have to enter this information later.
3. Start SLICEWare by double-clicking the desktop icon or go to Programs/SLICEWare.

If you have any questions about software installation, please contact support@dtsweb.com.

Communicating with the SLICE FMH System

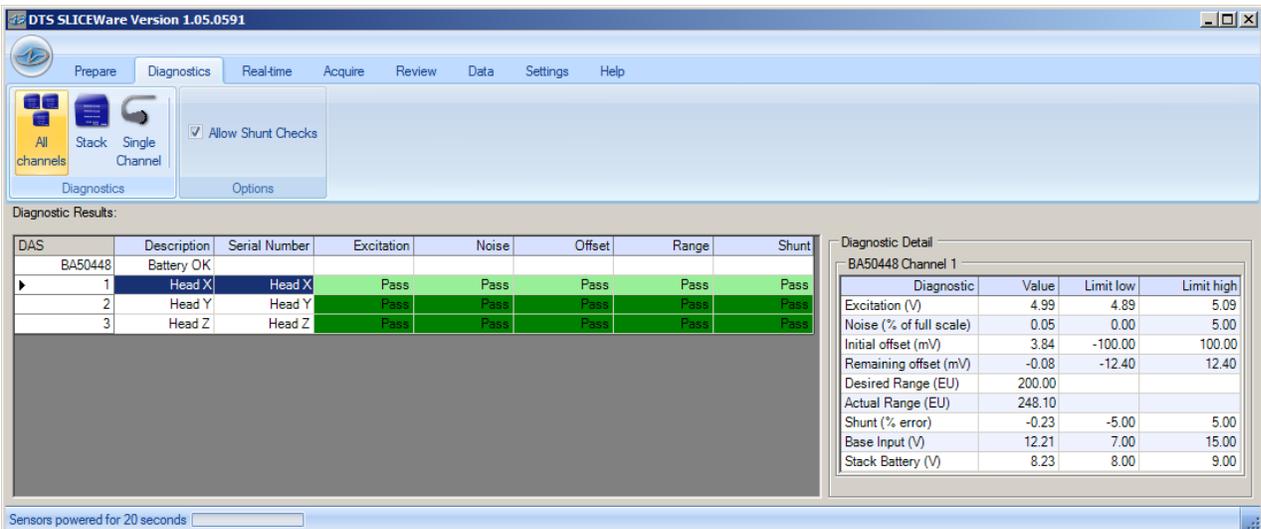
4. Connect cable 13000-30670 to the LEMO receptacle on the skull cap plate (Figure 5). Next, connect the cable to the power supply provided (Figure 6) and your PC. (The SLICE FHM system can be connected to the PC before or after starting the software.)
5. If you provided your own sensors or had to replace a sensor, you can manually enter the sensor information into the SLICEWare software before using your SLICE FMH system. (Check that the sensors that are installed in the FMH are visible on the  tab. If any sensor is missing, you need to manually install it.) You will need the calibration data provided with your sensors to do this. Each sensor must also be assigned to the correct axis and optional ISO code.

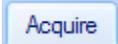


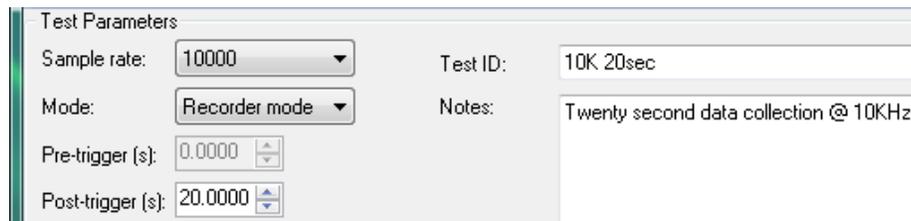
How to Auto-Arm the SLICE FMH System

The "Auto-Arm on Boot" feature allows users to automatically arm the system using user-selected parameters at system power-up/initialization. To use the auto-arm feature, all DAS in the test must support the auto-arm function.

- With SLICEWare running and the SLICE FMH system connected (step 4 above), go to the **Diagnostics** tab and perform a quick check to verify the hardware is working properly.



- Open the  tab. Complete the test set-up information (data collection mode, length of time, sample rate, etc.).



- Click the Auto-Arm button. Click OK.
- Close SLICEWare and disconnect cable 13000-30670 from the skull cap plate.
- To arm the system, press and hold the LED/pushbutton switch for >3 sec. After 7 sec, the LED will begin to blink, indicating the system is performing the auto-arm initialization sequence. After 32 sec, the LED will be either on (circular buffer mode) or off (recorder mode).

Troubleshooting

If the LED continues to blink after 45 sec, the system did not initialize properly. To clear the fault, reconnect the system to the power supply and PC (step 4 above), then start SLICEWare. Manually arm and test the SLICE FMH system to clear the fault. (You must clear the fault before the system will power down.) After clearing the fault, repeat steps 7-10 above.

Downloading Data

- Reconnect the system to the power supply and PC (step 4 above). Start SLICEWare.
- Open the  tab. To download the total time specified by the initial test

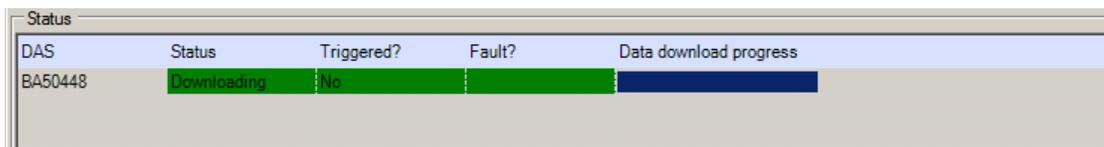
set-up, select . To download a region-of-interest only, enter the desired

timeframe (for example,

ROI Begin Time (sec)	-0.5
ROI End Time (sec)	0.5

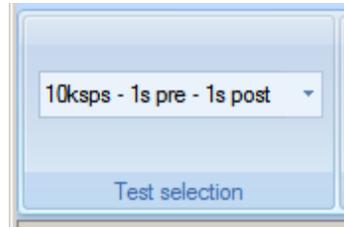
) and then select .

- Depending on the length of the test, it may take several minutes or longer to download the data. A download progress bar is shown in the center of the screen alongside the corresponding DAS.



Viewing Data

1. Open the **Review** tab. Available data sets for viewing are shown on the left. These data sets are stored on your PC, not the SLICE.



2. Selecting a test will load it in the viewing area.

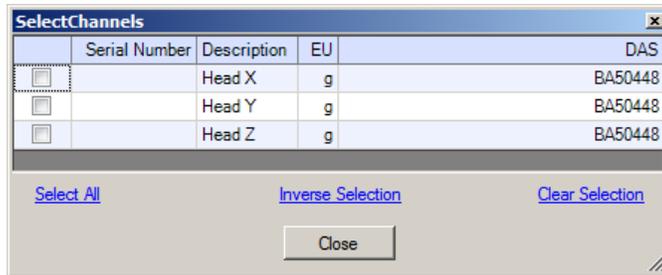


3. You can zoom using the  and  icons on the upper right of the screen. You can also zoom by selecting **Zoom** and then drawing a window around a region-of-interest.

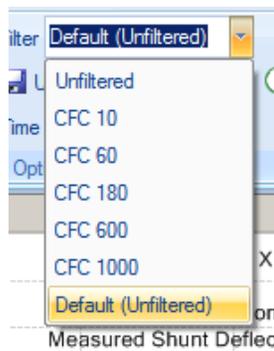
4. Multiple data channels can be viewed on the graph at one time. You can choose



which channels to view using

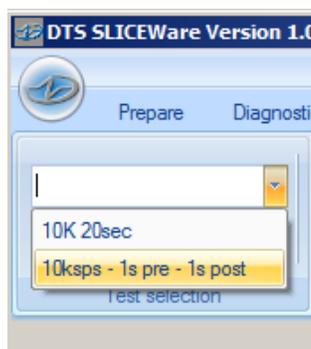


5. The data can be viewed unfiltered or using a selected filter.

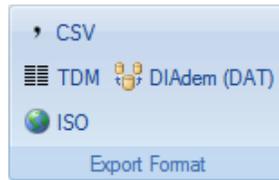


Exporting Data

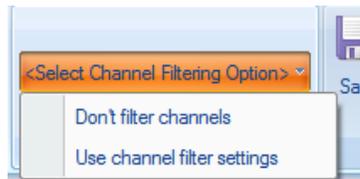
1. Open the **Data** tab and select the data set you wish to export from the tests available.



2. Select an export format for the data.



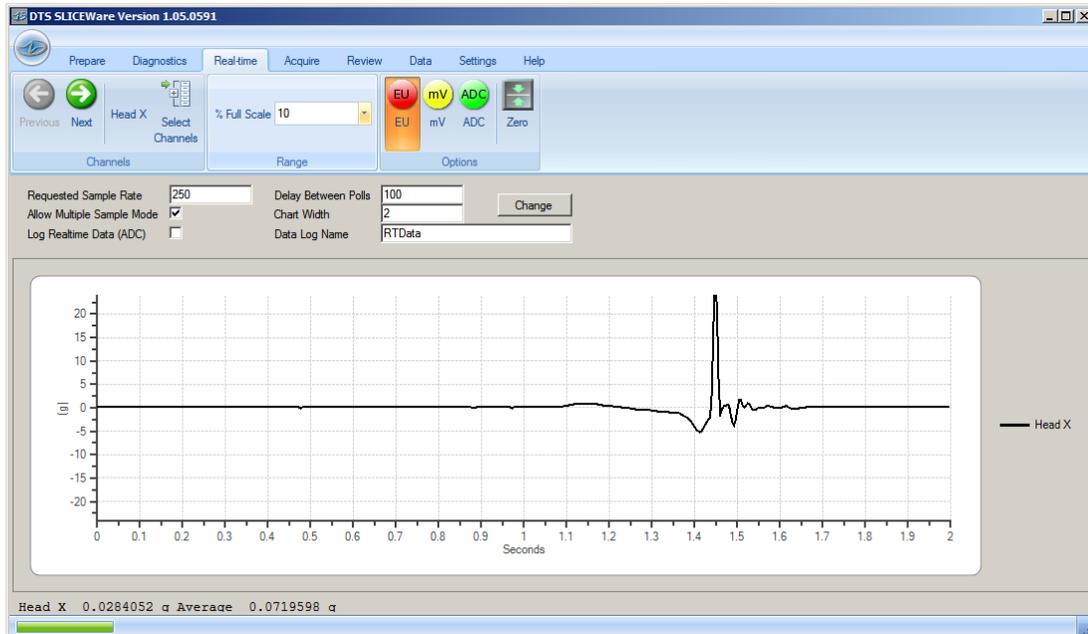
3. Select whether or not you want the exported data to be filtered or unfiltered. If filtered is selected, SLICEware will apply the software filter associated with each sensor in the test.



4. To export the data using the settings you selected above, select . A 'save as' dialog will open and allow you to choose where to save the exported data.

Real Time Mode

To view data from the channels real time, click the  tab. You can view any or all of the three channels. Note that the data is being sampled continuously at a relatively low sample rate. For example, you may not see a short duration data pulse when hitting the SLICE against a surface.



Specifications



BASE SLICE (MICRO & NANO)

Size:	MICRO 42 x 42 x 8 mm (1.65 x 1.65 x 0.32") NANO 26 x 31 x 6.5 mm (1.02 x 1.22 x 0.26")
Weight:	MICRO ~28 g (0.99 oz), NANO ~14.2 g (0.50 oz)
Connectors:	Omnetics, circular locking, 12-pin
Connectors:	MICRO integrated, NANO cable assembly

ENVIRONMENTAL

Operating Temp.:	0 to 60°C (32 to 140°F) Call to discuss extended temperature ranges
Humidity:	95% RH non-condensing
Shock:	500 g, 4 msec half sine 5000 g option (SLICE NANO) 50,000 g option (SLICE HG)

DATA RECORDING

Modes:	Recorder or circular buffer modes available.
Memory:	7 GB non-volatile flash per SLICE stack
Sample Rate:	Up to 120 ksp/s/channel Individual channel sample rate is determined by number of SLICES in each stack

TRIGGERING

Hardware Trigger:	Isolated contact closure & logic-level input
Level Trigger:	Software programmable from any channel(s)

POWER

Supply Voltage:	9-15 VDC; >11 VDC when using BATT SLICE
Current (Maximum):	100 mA. Each additional SLICE unit requires additional power (depends significantly on connected sensor load)
Power Control:	Remote power control input for on/off
Protection:	Reverse current, ESD

SOFTWARE

Control:	SLICEWare, API
Operating Systems:	Windows® XP/Vista/7
Communication:	USB; optional Ethernet interface



BRIDGE SLICE (MICRO & NANO)

Size:	MICRO 42 x 42 x 7 mm (1.65 x 1.65 x 0.32") NANO 26 x 31 x 5.5 mm (1.02 x 1.22 x 0.22")
Weight:	MICRO ~25 g (0.88 oz), NANO ~13.8 g (0.49 oz)
Connectors:	Omnetics, circular locking; 3 single-channel 7-pin or 1 three-channel 16-pin

SIGNAL CONDITIONING

Number of Channels:	3 differential, programmable
Input Range:	±2.4 V (2.5 V center)
Bandwidth:	DC to 40 kHz, programmable
Gain Range:	1.0-1280, programmable
Auto Offset Range:	100% of effective input range
Bridge Support:	Software switchable completion
Shunt Check:	Emulation method

ANALOG-TO-DIGITAL CONVERSION

Type:	16-bit SAR, one ADC per channel
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EXCITATION

Method:	One 20 mA current-limited source/channel
Voltage:	5.0 V
On/Off Control:	Shut down when not armed or recording Opt. pulsed excitation for low sampling rates

POWER

Voltage:	Supplied via BASE SLICE
Current (Maximum):	110 mA with 350 ohm bridges all channels Power will vary significantly with sensor load

ANTI-ALIAS FILTER

Fixed Low Pass:	4-pole Butterworth, standard knee frequency of 40 kHz
Adjustable Low Pass:	5-pole Butterworth set under software control, 50 Hz to 40 kHz
Overall Response:	Both filters may be used together to achieve 9-pole effective response
SAE J211:	System exceeds SAE J211 response



IEPE SLICE (MICRO Only)

Size:	MICRO 42 x 42 x 7 mm (1.65 x 1.65 x 0.28")
Weight:	~28 g (0.99 oz)
Connectors:	10-32 coaxial (Microdot-compatible)

SIGNAL CONDITIONING

Number of Channels:	3
Input Range:	0.5-23.5 V (12 V center)
Bandwidth:	DC to 40 kHz, programmable
Gain Options:	1 or 10, user programmable
Auto Offset Range:	100% of effective input range at gain of 1

ANALOG-TO-DIGITAL CONVERSION

Type:	16-bit SAR, one ADC per channel
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EXCITATION

Method:	One 2.2 mA constant-current source/channel
Voltage:	up to 24 V
On/Off Control:	Shut down when not armed or recording

POWER

Voltage:	Supplied via BASE SLICE
Current (Maximum):	70 mA with sensors connected to all channels

ANTI-ALIAS FILTER

Fixed Low Pass:	4-pole Butterworth, standard knee frequency of 40 kHz
Adjustable Low Pass:	5-pole Butterworth set under software control, 50 Hz to 40 kHz
Overall Response:	Both filters may be used together to achieve 9-pole effective response



ARS SLICE (MICRO Only)

Size:	MICRO 42 x 42 x 9 mm (1.65 x 1.65 x 0.35")
Weight:	~30 g (1.06 oz)
Number of Channels:	3
Range Options:	Triaxial, ±300, 1500, 8k, 12k, 50k deg/sec
Current (Maximum):	75 mA (power supplied via BASE SLICE)



ACCEL SLICE (MICRO Only)

Size:	MICRO 42 x 42 x 9 mm (1.65 x 1.65 x 0.35")
Weight:	~30 g (1.06 oz)
Number of Channels:	3
Range Options:	Triaxial, ±50, 100, 500 g
Current (Maximum):	65 mA (power supplied via BASE SLICE)



BATTERY SLICE (NANO Only)

Size:	NANO 26 x 31 x 4 mm (1.65 x 1.65 x 0.16")
Weight:	~7 g (0.25 oz)
Charge Status:	Backup battery charges when input voltage to BASE SLICE is greater than 11 VDC
Charge Time:	~15 min. from complete discharge to full charge (100 mA at input connector on Base)
Discharge Rate:	~16 seconds at 1 A ~2 minutes at 400 mA

SERVICES

24/7 Worldwide Tech Support
ISO 17025 (A2LA) Calibration
Onsite Calibration & Training
Application Consulting
Software Integration
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TECH CENTERS

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Novi, Michigan USA
Sydney, Australia
Shanghai, China
Zorge, Germany
Tokyo, Japan



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Specifications subject to change without notice.

Appendix B: Pin Assignments

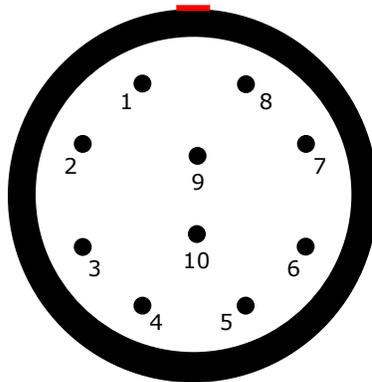
13000-30131 Termination Specifications



(looking into the connector)

Pin	Wire color	Function	Notes
1	Green	+Sig	
2	White	-Sig	
3	Red	+Ex	
4	Yellow	+ID	
5	Black	-Ex	
6	Shield	-ID/Shield	Solder bridge on pins 6 and 7

10-pin Interface Connector (ECG.1B.310.CLL)

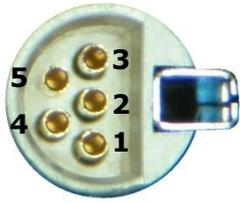


(panel view)

Pin	Function
1	/ON
2	/START
3	/EVENT
4	Status
5	12-15 VDC

Pin	Function
6	Ground
7	USB power
8	USB_DP
9	USB_DM
10	USB Ground

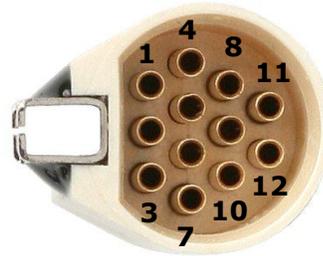
5-socket FMH Interface Connector



(looking into the connector)

Pin	Function
1	-Status
2	Ground
3	+Status
4	$\overline{\text{On}}$
5	$\overline{\text{Event}}$

12-socket FMH Interface Connector*



(looking into the connector)

Pin	Function
1	$\overline{\text{On}}$ (contact closure input to ground)
2	$\overline{\text{Start}}$ (contact closure input to ground)
3	$\overline{\text{Event}}$ (contact closure input to ground)
4	Status output (5 V via 10K with respect to ground)
5	12-15 VDC
6	12-15 VDC
7	Ground
8	Ground
9	USB_PWR
10	USB_DP
11	USB_DM
12	Ground

* These connectors are identical.

Appendix C: SLICE FMH Assembly Procedure

1. Mount the SLICE system and sensors to the neck load cell structural replacement using the proper hardware and recommended torque specifications by the FMH manufacturer. Carefully route all cables and use tie downs to create adequate strain relief and minimize cable movement. All mounting considerations should be thoroughly addressed to ensure the system is adequately integrated to survive the expected shock loads.



FMH Interface

The 12-socket connectors are functionally identical and either may be used to connect the Base SLICE "UP" connector or cable 13000-30680 (FMH interface to SLICE system).

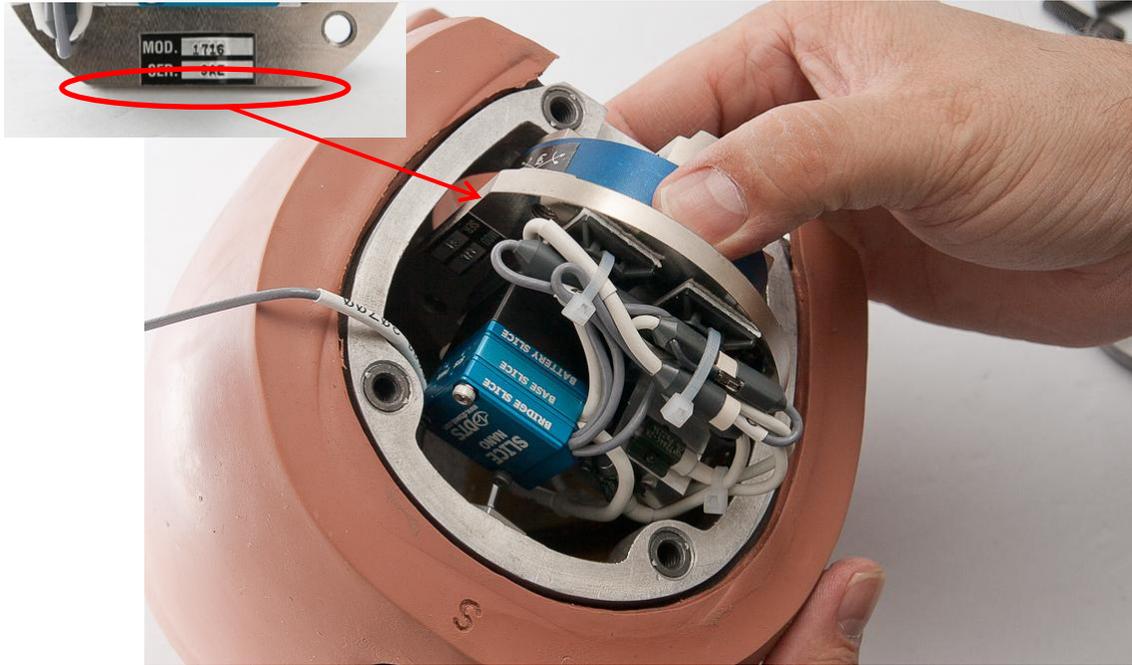
2. Attach cable 13000-30680 (FMH interface to SLICE system) to skull cap plate using the provided hardware. Tighten securely.



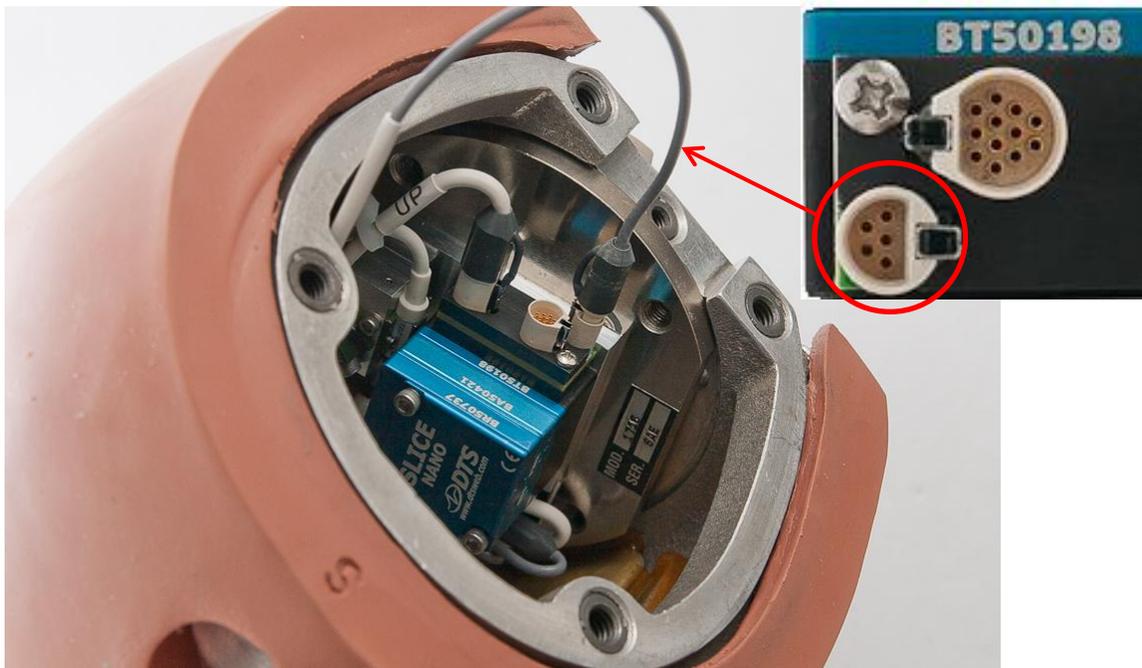
3. Attach cable 13000-30700 (SLICE FMH LED Pushbutton Cable Assembly) by threading it into the FMH skull. Tighten securely.



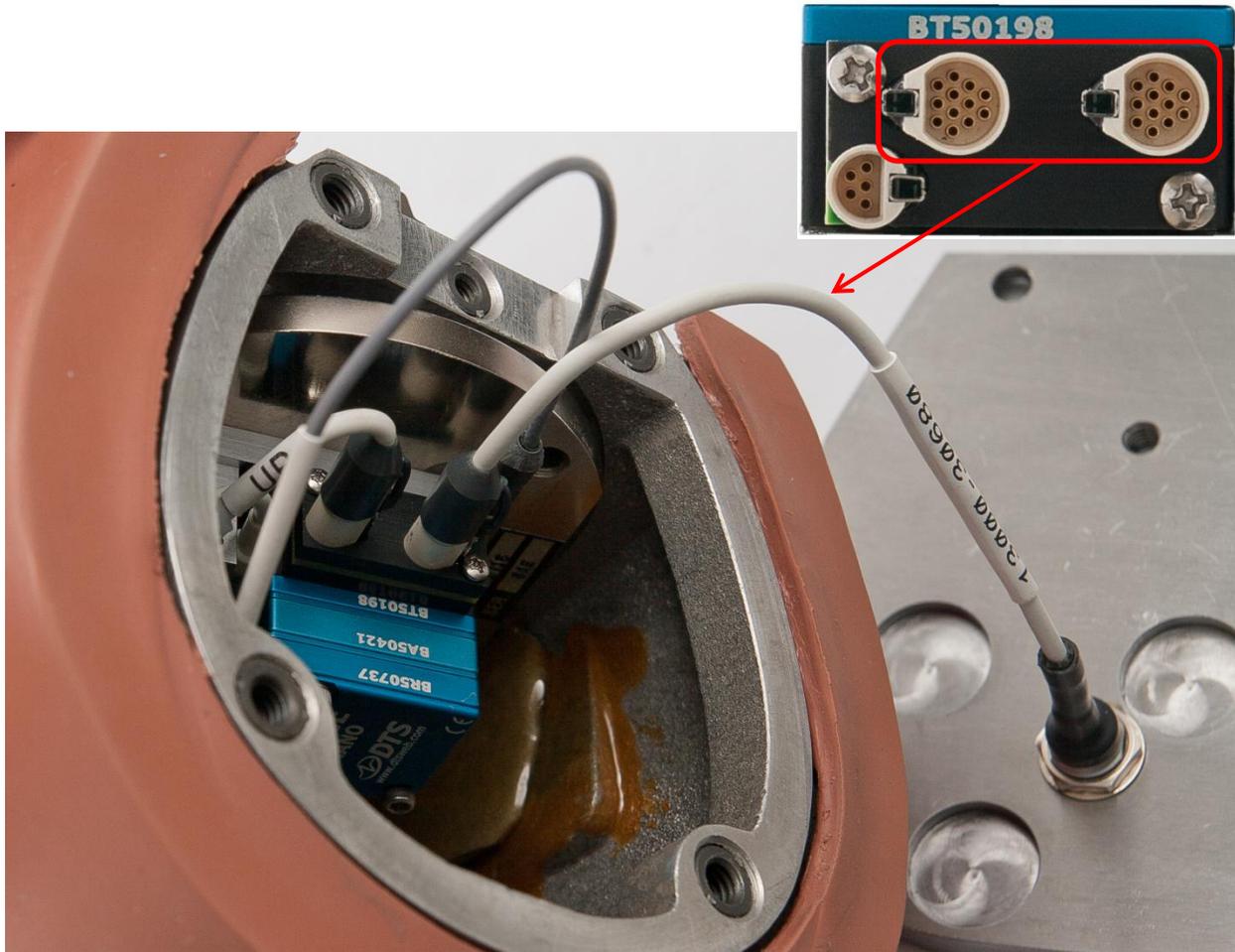
4. Insert neck load cell structural replacement into skull. Note the position of the flat edge relative to the FMH skull.



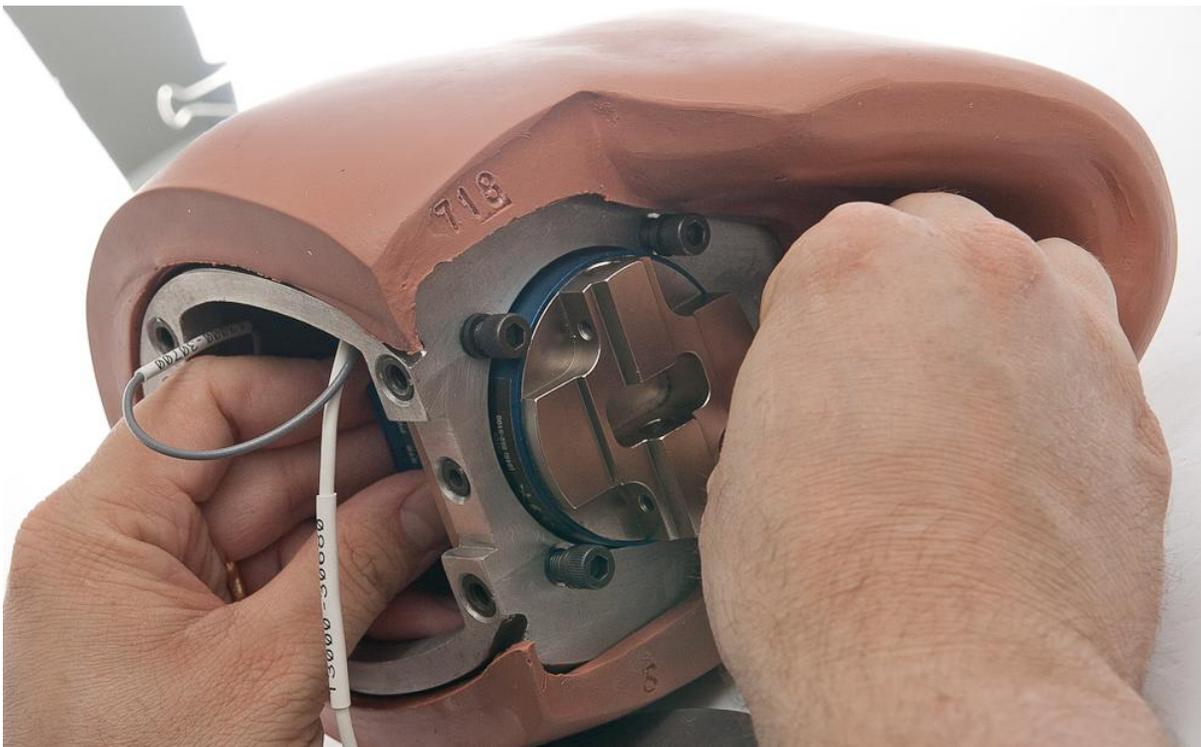
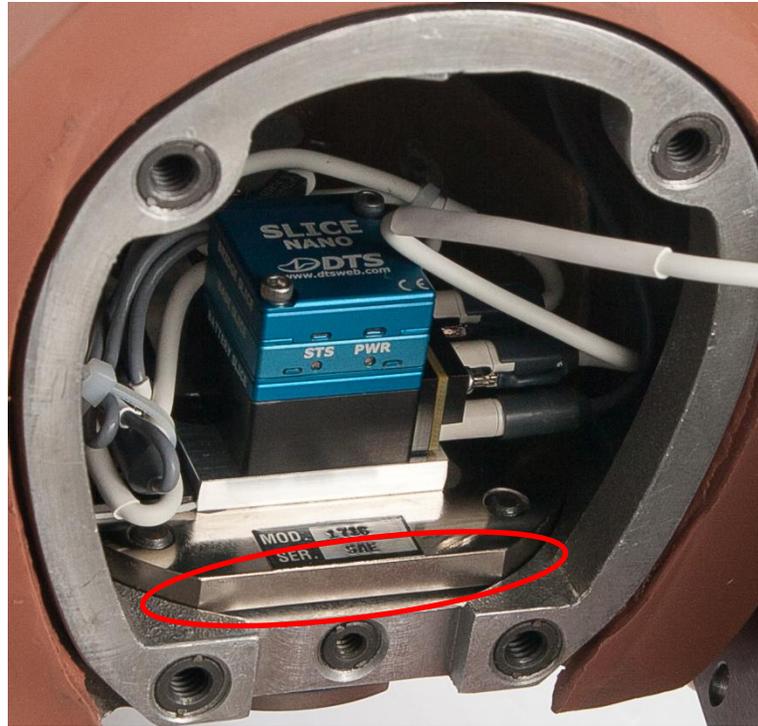
5. Rotate neck load cell structural replacement counter-clockwise so that the FMH interface is visible. Connect cable 13000-30700 (SLICE FMH LED Pushbutton Cable Assembly) to the FMH interface.



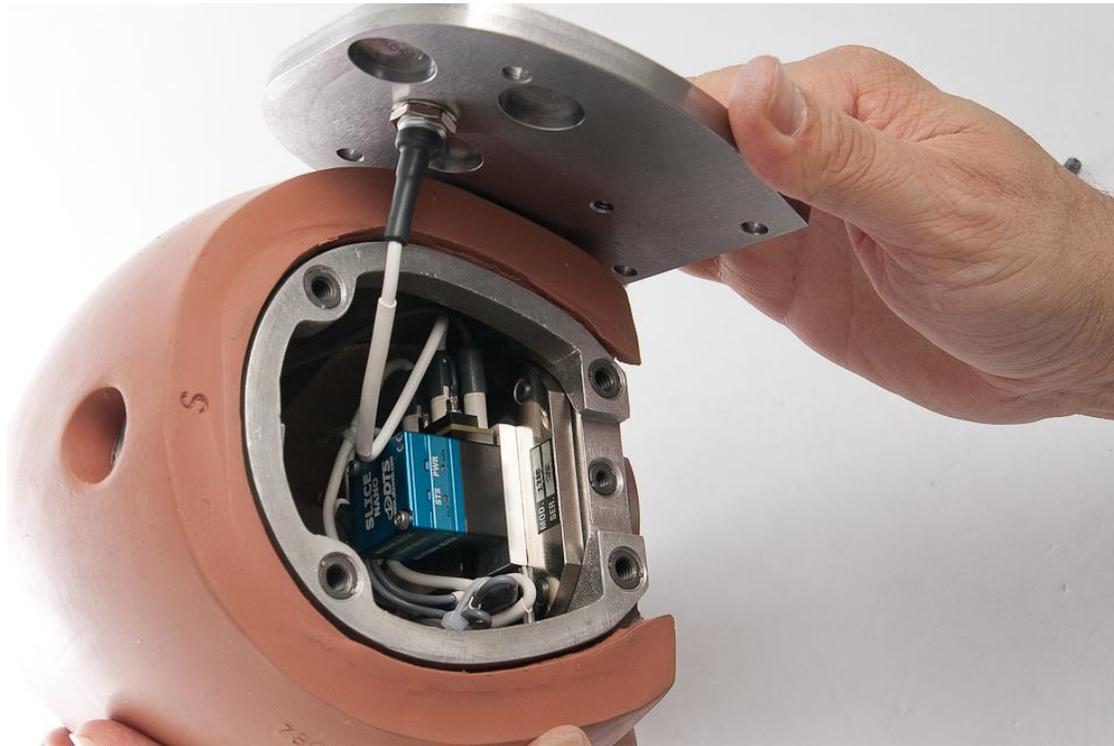
6. Connect cable 13000-30680 (FMH interface to SLICE system) to the FMH interface using the available 12-socket connector.



7. Rotate neck load cell structural replacement clockwise so that the flat edge of the neck load cell structural replacement is aligned properly. Secure it to the aluminum skull using the proper hardware and recommended torque specifications by the FMH manufacturer.



8. Route the cable into the skull and install the skull cap plate using the proper hardware and recommended torque specifications by the FMH manufacturer.



Appendix D: Minimizing System Self-Heating

Following the procedure outlined below will avoid any unnecessary heat generation in excess of $\sim 1^{\circ}\text{C}$.

1. Charge the system using a 12 V power supply. 12 V is the minimum required by the SLICE system; anything in excess will contribute to heat generation.

2. Do not connect your PC to the system while it is charging. While this prevents checking system status, continual PC communications keep the micro-processor active. If the battery is not completely discharged and you do not want to wait the maximum recharge time (1 hour), you may wish to implement a hardware interface that allows you to check battery charge status. When the input current drops to 75 mA, the battery is fully charged.

3. Complete the software auto-arm sequence and disconnect the system from the PC and power supply within 2 minutes. Completing this step quickly minimizes system and sensor self-heating. Once auto-arm and disconnect are completed, the system is in a low-power state and awaiting initialization.

4. Initialize the system and perform your test quickly. To initialize the system, press the LED/pushbutton switch for ≥ 3 sec. When the LED goes solid, the system is ready for testing. Performing your test as soon as possible after system initialization minimizes self-heating.

Revision History

Date	By	Description
13 Jul 2012	EKK	Initial release. (Rev 0)